

2012 Day 2 Question 4 (MHD)

1. $\nabla \cdot \mathbf{V} = 0$ (incompressible)

$$\nabla^2 \phi = 0$$

$$z > 0 \quad \nabla^2 (\phi_1(z) e^{i(kx - \omega t)}) = -k^2 \phi_1(z) + \phi_1''(z) = 0$$

$$\phi_1''(z) = k^2 \phi_1(z) \rightarrow \phi_1(z) = A e^{-kz} \quad (\text{choose } -kz \text{ to prevent blowup})$$

$$z < 0 \quad \text{Same calculation with } \phi_2(z) = B e^{kz}$$

2. $V_z = \frac{dz}{dt}$

$$z > 0 \quad (\partial_t + u_0 \partial_x) d e^{i(kx - \omega t)} = \partial_z A e^{-kz} e^{i(\cdot)}$$

$$(-i\omega + iku_0) d = -kA e^{-kz} \quad z \rightarrow 0^+$$

$$\rightarrow A = i(\omega - u_0 k) / k$$

$$z < 0 \quad (\partial_t - u_0 \partial_x) d e^{i(\cdot)} = \partial_z B e^{kz} e^{i(\cdot)}$$

$$(-i\omega - iku_0) d e^{ikz} = kB$$

$$\rightarrow B = -id(\omega + u_0 k) / k$$

3. $\rho \frac{dv}{dt} = -\nabla P$ Assume P also of the form $P(z) e^{i(kx - \omega t)}$

(not strictly necessary, could be derived from force balance explicitly)

$$z > 0 \quad \rho_0 (\partial_t + u_0 \partial_x) \cancel{\nabla \phi} = -\partial_x P$$

$$\rho_0 (-i\omega + iku_0) (ik) A e^{-kz} e^{i(\cdot)} = -ikP \quad z \rightarrow 0^+$$

$$\rho_0 i (-ku_0 + \omega) A = P_1$$

$$z < 0 \quad \rho_0 (\partial_t - u_0 \partial_x) \partial_x \phi = -\partial_x P$$

$$\rho_0 (-i\omega - iku_0) (ik) B e^{kz} = -ikP \quad z \rightarrow 0^-$$

$$\rho_0 i (\omega + ku_0) B = P_2$$

B.C. $P_1 = P_2$

$$\rightarrow -(\omega - u_0 k)^2 \rho_0 d = \rho_0 d (\omega + u_0 k)^2$$

Assuming some background density on both sides of the interface,

$$\omega = \pm i u_0 k, \quad \text{Im } \omega \neq 0 \text{ gives instability here.}$$

Note B_0 is uniform $B_0 \hat{x}$

$$4. \quad \nabla \times \vec{H} = \vec{E} + \vec{v} \times \vec{B}/c$$

$$\nabla \times \nabla \times \vec{H} = -\frac{1}{c^2} \vec{B} + \nabla \times (\vec{v} \times \vec{B})/c = 0 \quad \text{as } z \rightarrow 0 \quad (\text{ideal limit})$$

$$\nabla \times (\vec{v} \times \vec{B}) \approx \nabla \times (\vec{v} \times \vec{B}_1) + \nabla \times (\vec{v}_1 \times \vec{B}_0)$$

$$\begin{aligned} \nabla \times (\vec{v} \times \vec{B}_1) &= \vec{v} (\nabla \cdot \vec{B}_1) - \vec{B}_1 (\nabla \cdot \vec{v}) + (\vec{B}_1 \cdot \nabla) \vec{v} - (\vec{v} \cdot \nabla) \vec{B}_1 \\ &= -(v \cdot \nabla) \vec{B}_1 \end{aligned}$$

$$\nabla \times (\vec{v} \times \vec{B}_0) = (B_0 \cdot \nabla) \vec{v},$$

$$\Rightarrow \text{Let } \vec{B}_1 = \vec{B}(z) e^{i(kx - \omega t)}, \quad B_0 = B_0 \hat{u}_0$$

$$\begin{aligned} \text{in } \vec{B}(z) e^{i(kx - \omega t)} &= (B_0 \cdot \nabla) \vec{v}_1 - (v \cdot \nabla) \vec{B}_1 \\ &= B_0 \partial_x \vec{v}_1 - v_0 \partial_x B(z) e^{i(kx - \omega t)} \end{aligned}$$

$$\text{in } B_x = -A k^2 B_0 \phi_1 - i k v_0 B_x e^{i(kx - \omega t)}$$

$$i(k v_0 - \omega) B_x = -A k^2 B_0 A k \phi_1 e^{-kz} \quad B_x = \frac{-k^2}{i(k v_0 - \omega)} B_0 A e^{-kz} = B_0 k d$$

$$z < 0 \quad -i\omega B_x = +B_0 \partial_x^2 \phi_2 + v_0 \partial_x B(z) \\ = -k^2 B_0 B e^{kz} + i k v_0 B_x$$

$$B_x (-i)(\omega + k v_0) = -k^2 B_0 B e^{kz}$$

$$B_x = \frac{+k^2}{i(\omega + k v_0)} B_0 B e^{kz} = -B_0 k d$$

$$5. \quad P_1 + \frac{B_{x1} R_0}{8\pi} = P_2 + \frac{B_{x2} R_0}{8\pi} \\ -(\omega - v_0 k)^2 P_0 + \frac{R_0^2 k^2}{8\pi} = (\omega + v_0 k) P_0 \quad \Rightarrow -\frac{B_0^2 k^2}{8\pi}$$

$$\Rightarrow [(\omega + v_0 k)^2 + (\omega - v_0 k)^2] = \frac{k^2 R_0^2}{8\pi}$$

$$\Rightarrow (\omega^2 + (v_0 k)^2) = \frac{R_0^2}{P_0 8\pi}$$

$$\omega^2 = \frac{B_0^2 k^2}{P_0 8\pi} - \frac{v_0^2 k^2}{8\pi}$$

$$= k^2 \left(\frac{V_A^2}{2} - v_0^2 \right)$$

$$V_A^2 > 2v_0^2 \quad \text{for stability} \quad (\ln \omega = \sigma)$$