

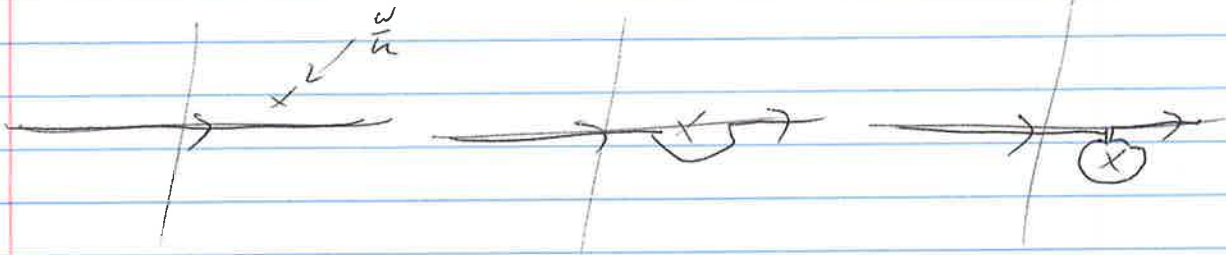
2018 Day 1 Question 4

a. Landau contour has three cases.

$\text{Im} \omega > 0$

$\text{Im} \omega = 0$

$\text{Im} \omega < 0$



b. Suppose there is an instability,  $\text{Im} \omega > 0$

$$1 + \frac{\omega p^2}{k^2} \int \frac{g'}{\frac{\omega}{k} - u} du = 0$$

$$1 + \frac{\omega p^2}{k^2} \int \frac{\frac{k}{\omega} (\frac{\omega}{k} - u + u)}{\frac{\omega}{k} - u} g' du = 1 + \frac{k \omega p^2}{\omega k^2} \int g' + \frac{u g'}{\frac{\omega}{k} - u} du$$

note  $\int g' du = g|_{-\infty}^{\infty} = 0$ .

$$= 1 + \frac{k \omega p^2}{\omega k^2} \int \frac{u g'}{\frac{\omega}{k} - u} du = 1 + \frac{k \omega p^2}{\omega k^2} \int \frac{(\frac{\omega}{k} - u) u g'}{|\frac{\omega}{k} - u|^2} du$$

Imaginary part gives  $\text{Im} \left( \frac{k \omega p^2}{k^2} \int \frac{(\frac{\omega}{k} - u) u g'}{|\frac{\omega}{k} - u|^2} du \right) = 0$ .

By assumption,  $u g' < 0 \forall u$ . And  $|\frac{\omega}{k} - u|^2$  clearly positive.

Imaginary part only:  $\text{Im} \omega \left( 1 - \frac{\omega p^2}{k^2} \int \frac{u g'}{|\frac{\omega}{k} - u|^2} du \right) = 0$

Since  $u g' < 0$  by assumption ( $g$  monotonically decreasing function of  $u^2$ ) and  $|\frac{\omega}{k} - u|^2 > 0$ ,  $\int \frac{u g'}{|\frac{\omega}{k} - u|^2} du < 0$ , hence

$$1 - \frac{\omega p^2}{k^2} \int \frac{u g'}{|\frac{\omega}{k} - u|^2} du \neq 0, \text{ so we have contradicted}$$

that  $\text{Im} \omega > 0 \rightarrow$  the system must be stable.

Keep for reference for when you do this problem.

$$1 + \frac{\omega p^2}{k^2} \int_L \frac{1}{\frac{\omega}{u} - v} \frac{\partial \epsilon}{\partial v} dv = 0$$

show  $\frac{\partial \epsilon}{\partial v} > 0 \rightarrow \ln \omega \approx 0$ .

→ 2013 Q1 (moderated)

$$\frac{v_H}{v_L} < \sqrt{\frac{B_{max}}{B_{min}} - 1} \quad B \approx B_0 \left(1 - \frac{r}{R} \cos \theta\right)$$

$$\frac{v_H}{v_L} < \sqrt{2\epsilon} \quad \rightarrow \begin{matrix} B_{max} = B_0(1+\epsilon) \\ B_{min} = B_0(1-\epsilon) \end{matrix}$$

→ stopped ~  $\sqrt{2\epsilon}$

marginal trapping:  $\frac{v_H}{v_L} = \sqrt{2\epsilon} \rightarrow v_H \sim v_L \sqrt{2\epsilon}$

$$P_4(r) = r m v_H + R_2 A(r) \quad \text{constant angle manner}$$

$$\Delta r \sim \frac{m v_H}{e B_p} \sim \frac{2 p_L}{\sqrt{\epsilon}}$$

$$J = e v_H \frac{\Delta r}{2r} \sim \frac{2 \sqrt{\epsilon} \partial P}{\sqrt{B_p} \partial r}$$