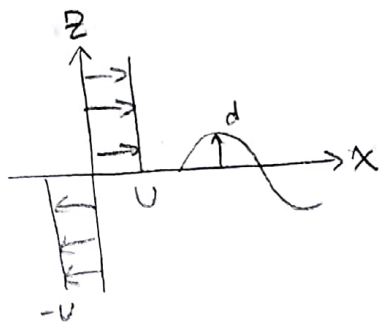


2012 II: Q4 MHD



incompressible, ideal

$$\vec{u}_0 = \begin{cases} (u, 0, 0) & z > 0 \\ (-u, 0, 0) & z < 0 \end{cases}$$

1.)  $\vec{u} = \vec{u}_0 + \vec{v}(x, z)$  where  $\vec{v}(x, z) = \nabla \phi$

incompressible:  $\nabla \cdot \vec{v} = 0$  so  $\nabla^2 \phi = 0$

for  $z > 0$ ,  $\nabla^2 \phi_1(z) e^{ik(x-ct)} = 0$

$$\Rightarrow -k^2 \phi_1(z) e^{ik(x-ct)} + \phi_1''(z) e^{ik(x-ct)} = 0$$

$$\phi_1''(z) = k^2 \phi_1(z)$$

$$\phi_1(z) = c_1 e^{kz} + c_2 e^{-kz} \quad \phi(\infty) = 0$$

$$\boxed{\begin{aligned} \phi_1(z) &= A e^{-kz} \\ \phi_2(z) &= B e^{kz} \end{aligned}}$$

similarly

2.) Suppose  $\xi = d e^{ik(x-ct)}$ ,  $v_z = \frac{D\xi}{Dt} = \frac{\partial \xi}{\partial t} + (\vec{u} \cdot \nabla) \xi = \frac{\partial}{\partial z} \phi$

for  $z > 0$ ,  $d(-ikc) e^{ik(x-ct)} + u d(ik) e^{ik(x-ct)} = A(-k) e^{-kz} e^{ik(x-ct)}$

$$\boxed{\begin{aligned} A &= -id(u-c) \\ B &= -id(u+c) \end{aligned}}$$

3.)  $p_1 \equiv p(z \rightarrow +\infty)$

In this case the momentum equation is  $\rho \frac{D\vec{v}}{Dt} = \vec{\nabla} \times \vec{B} - \nabla P$

$$\rho \left( \frac{\partial}{\partial t} + u \frac{\partial}{\partial x} \right) \nabla \phi = -\nabla P \quad \text{assume } P \sim p(z) e^{ik(x-ct)}$$

$$z \rightarrow +\infty \Rightarrow \rho \left( \frac{\partial}{\partial t} + u \frac{\partial}{\partial x} \right) ik A e^{ik(x-ct)} = -ik p_1 e^{ik(x-ct)}$$

$$\rho(-ikc + iku) A = -p_1$$

similarly,  $p_2 = -\rho B(-ikc - iku)$

$$p_1 = p_2 \Rightarrow B(-ikc - iku) = A(-ikc + iku)$$

$$(kc + ku)(kc + ku) = (ku - kc)(kc - ku)$$

$$(kc)^2 + 2(ku)(kc) + (ku)^2 = -(ku)^2 - (kc)^2 + 2(kc)(ku)$$

dispersion relation  $\Rightarrow$   $kc = \pm iku$

This system is unstable if  $\text{Im}(kc = \omega) > 0$ , which corresponds to  $u \neq 0$ .

4.) Impose  $\vec{B}_0 = B_0 \hat{x}$

$$\vec{E} + \vec{v} \times \vec{B} = 0 \quad \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\Rightarrow \nabla \times (\vec{v} \times \vec{B}) = +\frac{\partial \vec{B}}{\partial t}$$

$$\vec{v} = \vec{u}_0 + \vec{v}_1, \quad \vec{B} = \vec{B}_0 + \vec{B}_1$$

$$\nabla \times (\vec{v}_0 \times \vec{B}_0) + \nabla \times (\vec{v}_1 \times \vec{B}_0) + \nabla \times (\vec{v}_0 \times \vec{B}_1) = +\frac{\partial \vec{B}_1}{\partial t}$$

$$\nabla \cdot \vec{B} = 0, \quad \nabla \cdot \vec{v} = 0$$

$$\Rightarrow (\vec{B}_0 \cdot \nabla) \vec{v}_1 - (\vec{v}_1 \cdot \nabla) \vec{B}_0 + (\vec{B}_1 \cdot \nabla) \vec{v}_0 - (\vec{v}_0 \cdot \nabla) \vec{B}_1 = +\frac{\partial \vec{B}_1}{\partial t}$$

$$B_0 \left(\frac{\partial}{\partial x}\right)^2 \phi - u \frac{\partial}{\partial x} B_1 = \frac{\partial}{\partial t} B_1$$

$$z > 0: B_0 (ik)^2 \phi_1(z) e^{ik(x-ct)} - B_x u (ik) e^{ik(x-ct)} = B_x (-ikc) e^{ik(x-ct)}$$

$$B_x (ikc + iku) = B_0 (-k^2) \phi_1(z)$$

$$B_x = -\frac{k^2}{iku - ikc} B_0 \phi_1(z) = k B_0 d$$

for  $z < 0$ :

$$B_x = \frac{k^2}{iku + ikc} B_0 \phi_2(z) = -k B_0 d$$

$$p_1 + \frac{B_x B_0}{\mu_0} = p_2 + \frac{B_x B_0}{\mu_0}$$

$$-\rho(-ikc + iku)(-i\omega(u-c)) + \frac{B_0^2}{\mu_0} k^2 = -\rho(-ikc - iku)(-i\omega(u+c)) - \frac{B_0^2}{\mu_0} k^2$$

$$\frac{2B_0^2}{\mu_0} = \rho \left[ (-ic + iu)(-i\omega(u-c)) - (-ic - iu)(-i\omega(u+c)) \right]$$

$$\frac{2B_0^2}{\mu_0} = -\rho \left[ \underbrace{(-c+u)(-u+c)}_{2uc - u^2 - c^2} - \underbrace{(-c-u)(-u-c)}_{-u^2 - c^2 - 2uc} \right]$$

$$V_A^2 = \frac{B_0^2}{\mu_0 \rho}$$

$$\frac{2B_0^2}{\mu_0} = +\rho \left[ +2u^2 + c^2 \right] \Rightarrow \boxed{u^2 + c^2 = V_A^2}$$

Need  $\text{Im}(kc = \omega) > 0$  for instability

$$(kc)^2 = k^2(V_A^2 - u^2)$$

$$k^2(V_A^2 - u^2) \geq 0 \quad \text{if} \quad V_A^2 \geq u^2 \Rightarrow \frac{B_0^2}{\mu_0 \rho} \geq u^2$$

so  $B_0^2 \geq \mu_0 \rho u^2$  will stabilize the instability

or, if we shift reference frames,  $V_A \geq \frac{1}{2}|u_1 - u_2|$